

## FACULTY OF ENGINEERING B.E. 2/4 (EE/Inst.) I Semester (Main) Examination, December 2010 ELECTRICAL MEASUREMENTS AND INSTRUMENTS

Part - A

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Time : 3 Hours]

Note : Answer all Questions of from Part – B.

[Max. Marks: 75

13, a) Explain the construct

Answer five Questions

	from Part – B.	
	PART – A (25 Mar	ks)
1.	A measuring instrument with moving element is underdamped. Sketch the typical response of the moving system. When the measured parameter undergoes a step change in its value.	2
2.	Mention any four advantages of digital measurements compared to analog measurements.	2
3.	How is friction compensation effected in induction type energy meters ?	3
4.	What are the conditions to be statisfied for proper synchronization of two 3-ph alternators ?	3
5.	What are the difficulties encountered if wheatstone bridge is used for low resistance measurement?	3
6.	Draw the diagram of a Schering bridge. Mention the applications.	2
7.	Mention the distinguishing features between ballistic galvanometer and flux meter.	2
8.	Sketch the arrangement for determination of leakage factor in a 2-pole D.C. machine.	3
9.	Draw the circuit of a polar type potentiometer.	2
10.	How is an ammeter calibrated using potentiometer ? Draw the Circuit and mention the steps.	3

PART - B

11. a) Derive the expression for the driving torque in moving coil instrument.

b) With a neat sketch explain the working of moving iron instrument.

- 12. a) Explain how the range of moving coil instruments can be extended.
- 20 as here b) Explain the working of electrostatic instruments.
  - 13. a) Explain the constructional features and working of 1-ph energy meters.
    - b) What are the main sources of error in energy meters of induction type ? How can they be compensated ?
- 14. Explain the construction and principle of working of the following :
  - a) Weston synchroscope

- b) Resonance type frequency meter. typical response of the moving
  - 15. The four arms of a bridge are :
    - arm 'ab' : an imperfect capacitor  $C_1$  with an equivalent series resistance of  $r_1$ . arm 'bc' : a non-inductive resistance  $R_3$ .
    - arm 'cd' : a non-inductive resistance  $R_4$ .
    - arm 'da': an imperfect capacitor  $C_2$  with an equivalent resistance of  $r_2$  in series with a resistance  $R_2$ .
  - A supply of 450 Hz is given between terminals 'a' and 'c' and the detector is connected between 'b' and 'd'. At balance :

 $R_2 = 4.8\Omega$ ,  $R_3 = 2000\Omega$ ,  $R_4 = 2850\Omega$ , and  $C_2 = 0.5\mu$  F and  $r_2 = 0.4\Omega$ . Calculate the value of  $C_1$  and  $r_1$  and also of the dissipating factor for this capacitor.

16. a) Explain how B-H curve and hysterisis loop are determined using CRO.

- b) Explain how leakage factor is determined.
- 17. A current transformer having a 1 turn primary is rated at 500/5A, 50 Hz with an output of 15 VA. At rated load with non-inductive burden, the in-phase and quadrature components (referred to the flux) of the exciting mmf are 8 and 10 A respectively. The number of turns in the secondary is 98, and the resistance and leakage reactance of the secondary winding are  $0.35\Omega$  and  $0.3\Omega$ respectively. Calculate the ratio and phase angle errors.