

Code No.: 3135

FACULTY OF ENGINEERING B.E. 4/4 (ECE) I Semester (Main) Examination, December 2010 EMBEDDED SYSTEMS (Elective – I)

Time: 3 Hours]

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b) Discuss about advantage

Note: Answer all questions from Bart A. Answer any five questions from Part B.

	PART – A om gnilubertes 2019 nisler (25 Marl	ks)
1.	Differentiate between Hard and Soft real-time system.	3
2.	How does a Embedded Processor differ from a general purpose processor ?	2
3.	Explain TDMI with respect to ARM to Processors.	2
4.	List out the logical instructions in ARMFTDMI with an example.	3
5.	Distinguish between synchronous and Iso-synchronous communication.	2
6.	What are the advantages and disadvantages of interrupt driven data transfer?	3
7.	What is the difference between spin-lock and semaphores?	2
8.	How does a mailbox message differ from a queue message?	2
9.	Why do you need cross compiler?	3
10.	Define following terms:	3
	a) Watchdog Timer b) Multitasking c) RTOS.	

(50 Marks) PART - B 11. a) Explain software tools in designing of an Embedded system. b) Briefly explain classifications of Embedded system. 12. a) Explain the instruction set for power Po architecture. b) Discuss about advantages and disadvantages of Embedded Programming in 'C'. 13. a) Explain about a) I²C bus b) CAN bus c) USB bus. b) Draw the frame format of HDLC protocol and explain. 14. a) Explain RTOS scheduling models in detail. b) Briefly explain the inter process communication. 15. a) Discuss about processor selection for an Embedded system design. b) Explain embedded system project management and design issues in development process. 16. a) Explain the Hardware and Software features of AVR microcontroller. b) Discuss about multithreaded programming. 5. Distinguish between synchronous and Iso-synchronous communication. 17. Write short notes on: a) Memory management. The appares beautiful as a second se V. What is the difference between spin-lock and semaph agood gnitisw belloq (d c) Interrupt-driven I/O.